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2.1. (a) We know

that  $y_i[n] =$

$x[n] * h[n] = \sum_k$

$h[k]x[n-k]$  (S2.1-1)

The

signals  $x[n]$  and

$h[n]$  are as shown

in Figure S2.1. , - t

W A 2 . 4 h W 3 0 t

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Figure S2.1 From this figure, we can easily see that the above convolution sum reduces to

$$y_i[n] = \frac{1}{2}x[n-1] + \frac{1}{2}x[n+1]$$

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systems The  
second operator  $H$   
 $inv$  is the inverse of  
the first operator  $H$ .  
Hence, the input  $x(t)$   
is passed through

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the cascade  
connection of  $H$  and  
 $H^{-1}$  completely  
unchanged. Signals  
two situations  
equivalent, provided  
the  $H$  is time  
invariant.

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